



ULTRACAM

CALIBRATING THE NEW ULTRACAM OSPREY OBLIQUE AERIAL SENSOR

**EuroCOW 2014
Castelldefels, February 2014**

**Michael Gruber
michgrub@microsoft.com**



UltraCam Osprey



Combine Nadir and Oblique



UltraCam Osprey

- **Camera design**
 - 3rd generation UltraCam architecture
 - 2.0 seconds frame rate
 - 3.3 TB SSD storage
- **Camera Operation**
 - 10cm GSD (nadir) @ 850m AGL
 - Wing image GSD between 7.5cm (inner) and 12.5cm (outer) on a flat terrain
 - 80% frontlap @ 145kts

UltraCam Osprey

Focal Lens/ Pixel Size

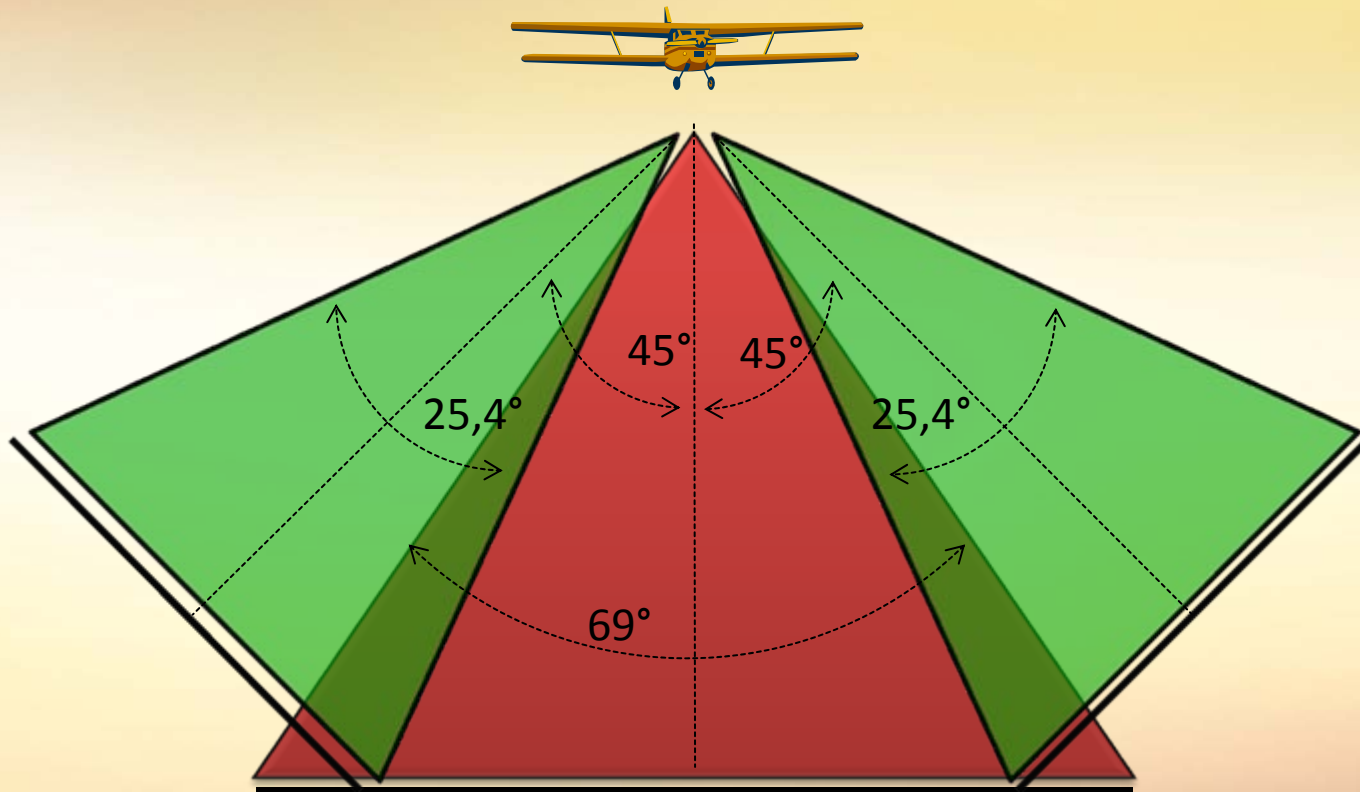
Nadir PAN	51.0 mm	6.0 μm
Nadir RGB and NIR	25.5 mm	5.2 μm
Oblique Sensor Heads	80.0 mm	5.2 μm

Frame Format / Pixel Size

Nadir PAN	11674 * 7514	6.0 μm
Nadir RGB and NIR	6735 * 4335	5.2 μm
Oblique Sensor Heads	6870 * 4520	5.2 μm
Fwd/Bwd (together)	13490 * 4520	

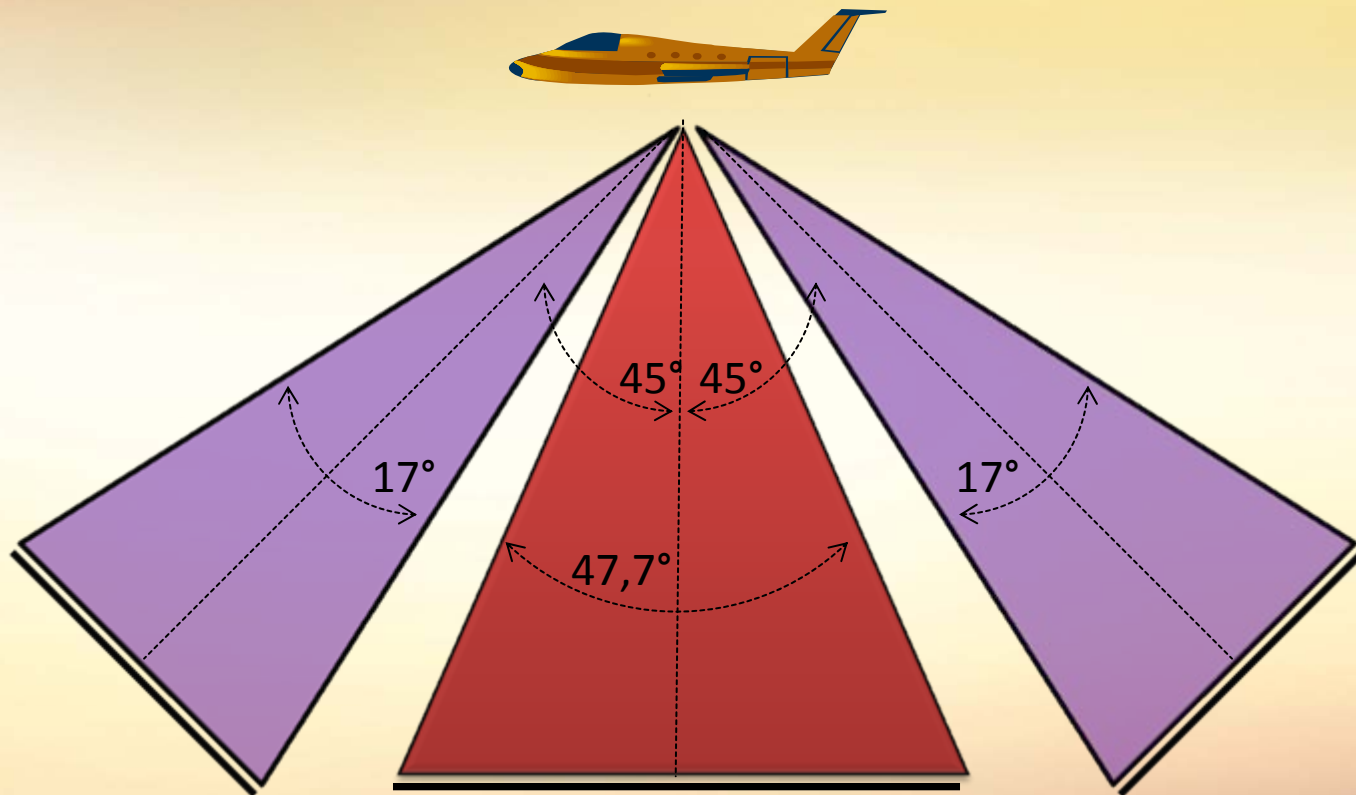
UltraCam Osprey

Nadir and L/R wing cross flight direction

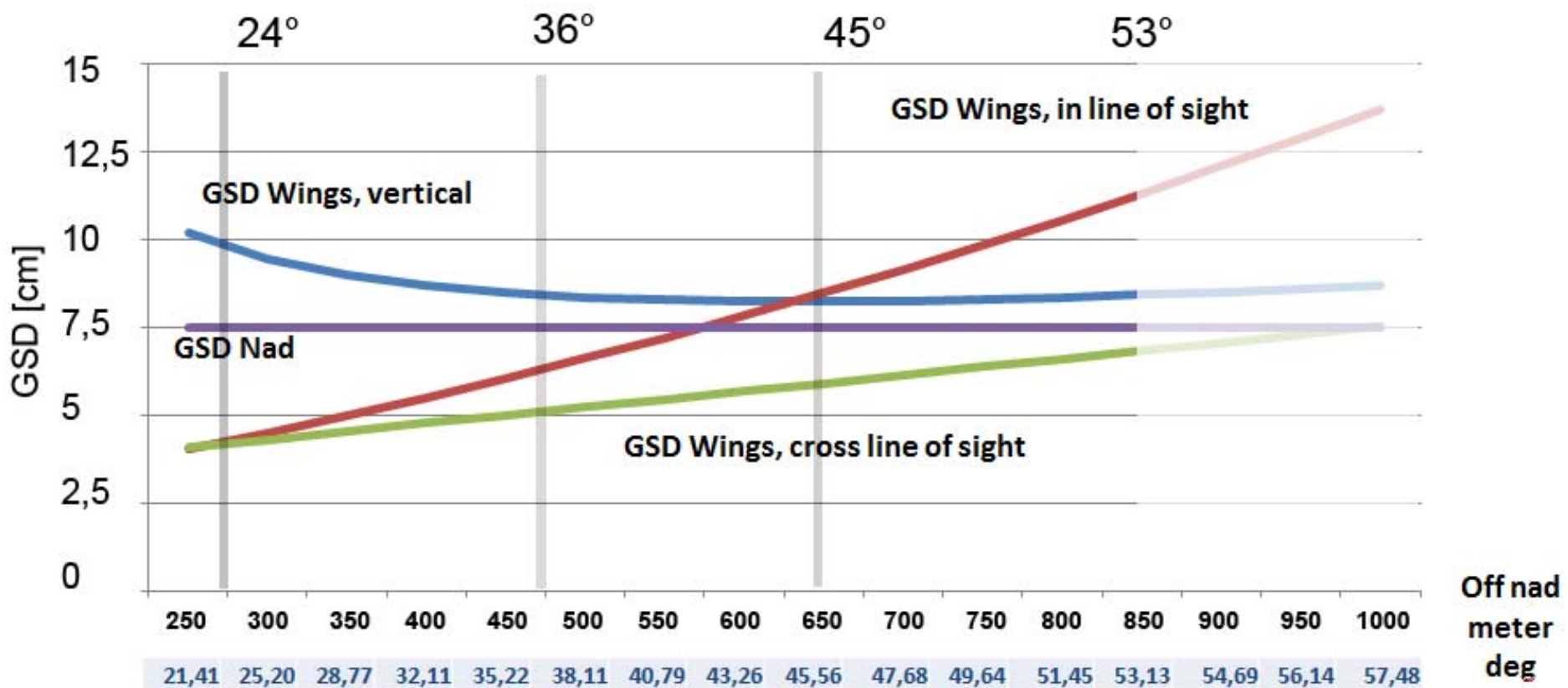


UltraCam Osprey

Nadir and F/B wing along flight direction



Spatial Resolution UltraCam O
 GSD Nad = 7,5 cm, H_agl 637 m





City of Graz, 900 m AGL, Nadir GSD 10,5 cm
Footprint 1230 m by 800 m

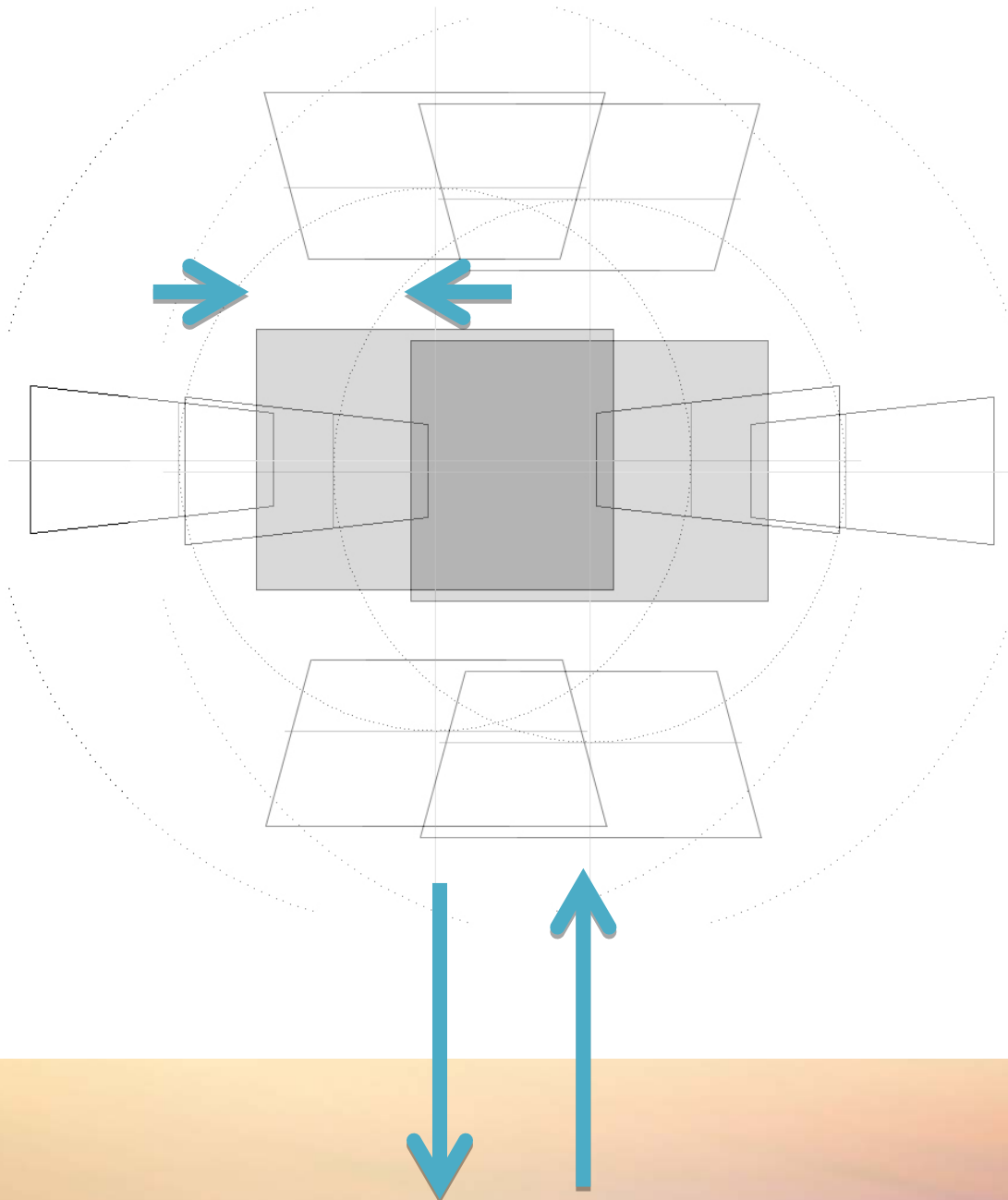




Forward Wing, 13490 Pixel cross track
Footprint ~1100 m cross track

ULTRACAM





**Ideal Flightpattern
60% cross track (Nadir)**

**Linespacing 500m
@ 900 m AGL**

UltraCam Osprey Calibration

Extended Calibration Lab

RMSE of Image Points $< 0,5$ Pixel

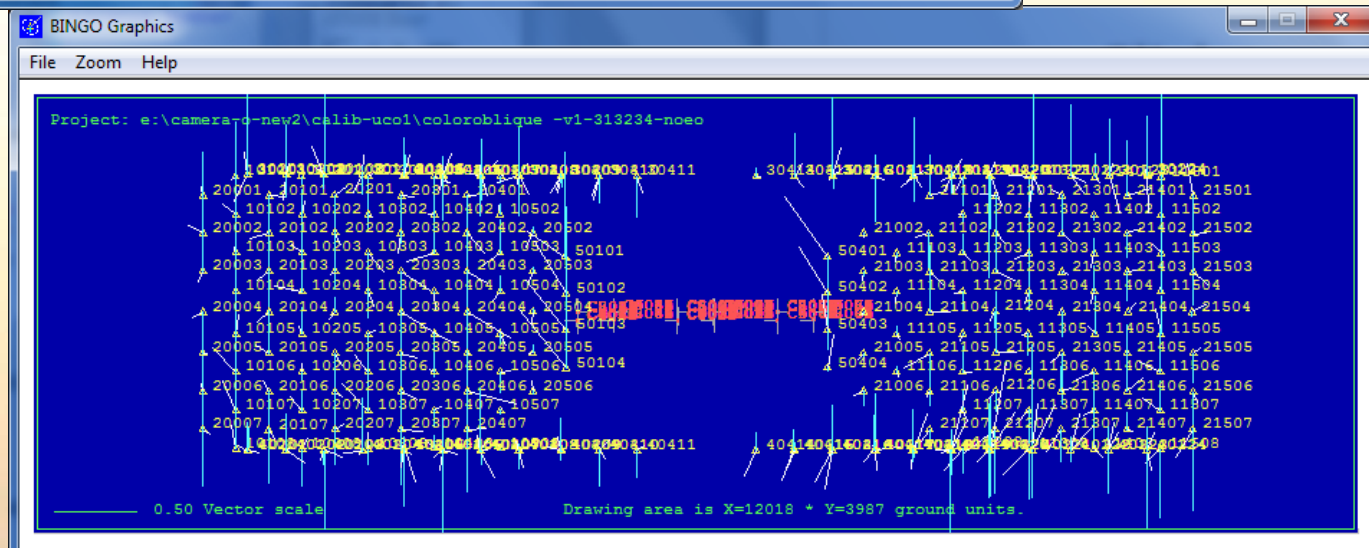
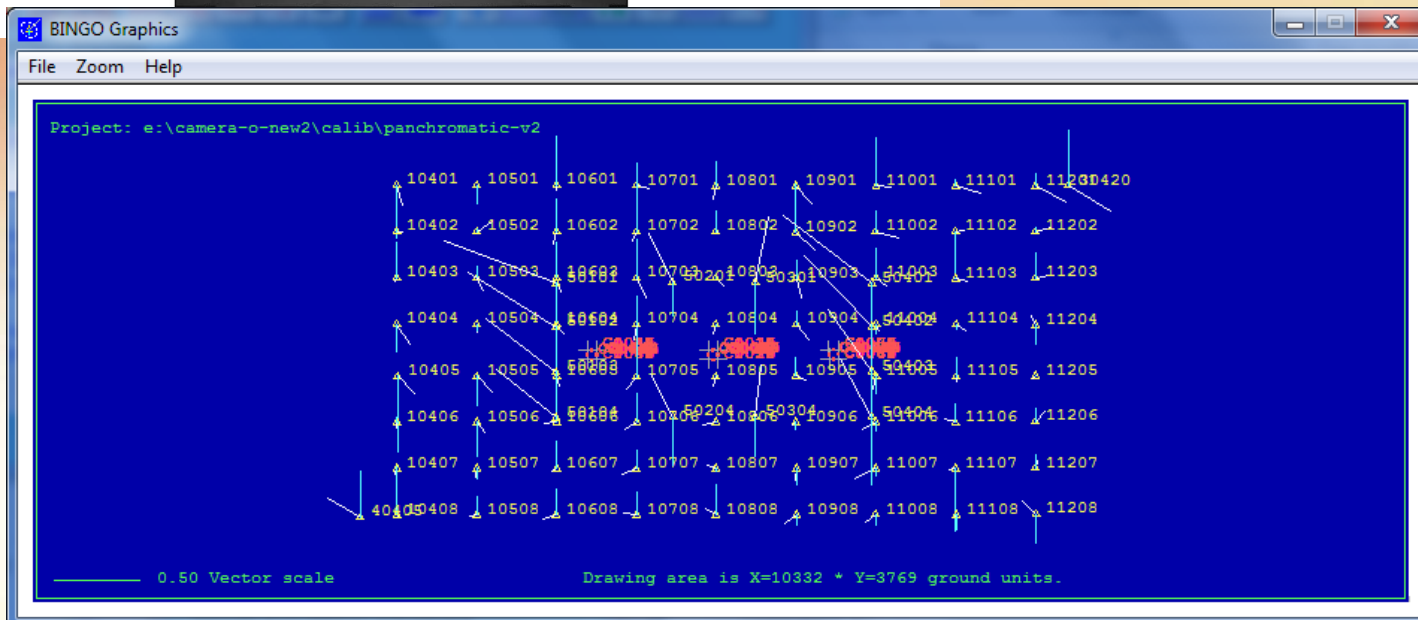
Redundant set of images

Single Head Calibration and Platform Calibration

Nadir EO results used for eccentricity computation

06

07



RESULTS OF ADJUSTMENT

Nadir PAN

SIGMA θ = 0.95

SIGMA θ = 0.79

RMS precision values of photo orientations from Qxx matrix

(X,Y,Z,phi,omega,kappa): (1/1000)

200. 99. 204. 3.6 2.9 1.6

Poorest precision values of photo orientations from Qxx matrix

(X,Y,Z,phi,ome,kap): (1/1000)

324. 135. 314. 12.3 10.1 9.7

Eccentricities of oblique cameras wrt nadir

C4	-37.9675	124.4535	-103.4782	0.1110	-49.8492	0.0290
C5	36.6477	124.0719	-103.2620	0.4059	-50.0955	-0.0748
C6	-125.7413	-37.9701	-106.0217	-49.9858	-0.0584	-0.0007
C7	125.6432	-37.8230	-105.9708	50.0001	0.0764	0.0367
C8	-37.4731	-124.2071	-104.4258	-0.3107	49.9585	-0.1362
C9	37.0895	-124.1808	-103.8412	0.0621	49.9728	-0.1330

RESULTS from oblique cameras

RMS control point residuals:	184.	175.	469. (1/1000)
Maximum control point residuals:	1073.	637.	2182. (1/1000)

RMS position residuals:	77.	64.	71. (1/1000)
Maximum position residual:	329.	255.	263. (1/1000)

RMS orientation residuals:	1.3	2.6	4.4 (1/1000)
Maximum orientation residuals:	3.5	7.8	12.8 (1/1000)

Nadir

RMS control point residuals:	114.	154.	176. (1/1000)
Maximum control point residuals:	599.	822.	656. (1/1000)

UltraCam Osprey Aerotriangulation

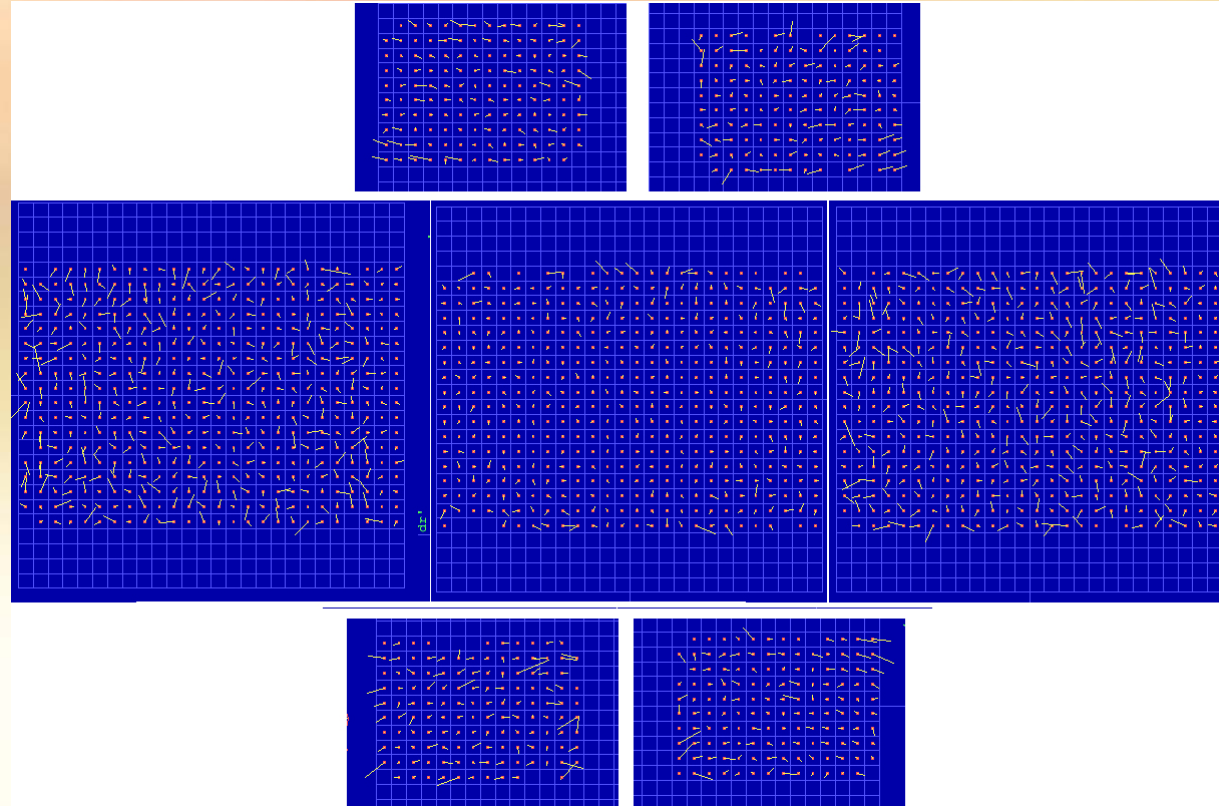
Project Area Graz
GSD Nadir 10 cm



```

3      86      87      164      165
4      85      88      163      166
5      84      89      162      167
6      83      90      161      168
W000007W000082W000009W000160W000169
W000008W000081W000012W000159W000170
W000009W000080W000013W000158W000171
W000010W000079W000014W000157W000172
W000011W000078W000015W000156W000173
W000012W000077W000016W000155W000174
W000013W000076W000017W000154W000175
W000014W000075W000018W000153W000176
W000015W000074W000019W000152W000177
W000016W000073W000020W000151W000178
W000017W000072W000021W000150W000179
W000018W000071W000022W000149W000180
W000019W000070W000023W000148W000181
W000020W000069W000024W000147W000182
W000021W000068W000025W000146W000183
W000022W000067W000026W000145W000184
W000023W000066W000027W000144W000185
W000024W000065W000028W000143W000186
W000025W000064W000029W000142W000187
W000026W000063W000030W000141W000188
27     62     111     140     189
28     61     112     139     190
29     60     113     138     191

```



RESULTS OF ADJUSTMENT

SIGMA 0 = 2.82

RMS control point residuals: 34. 33. 43. (mm)

Maximum control point residuals: 76. 72. 93. (mm)

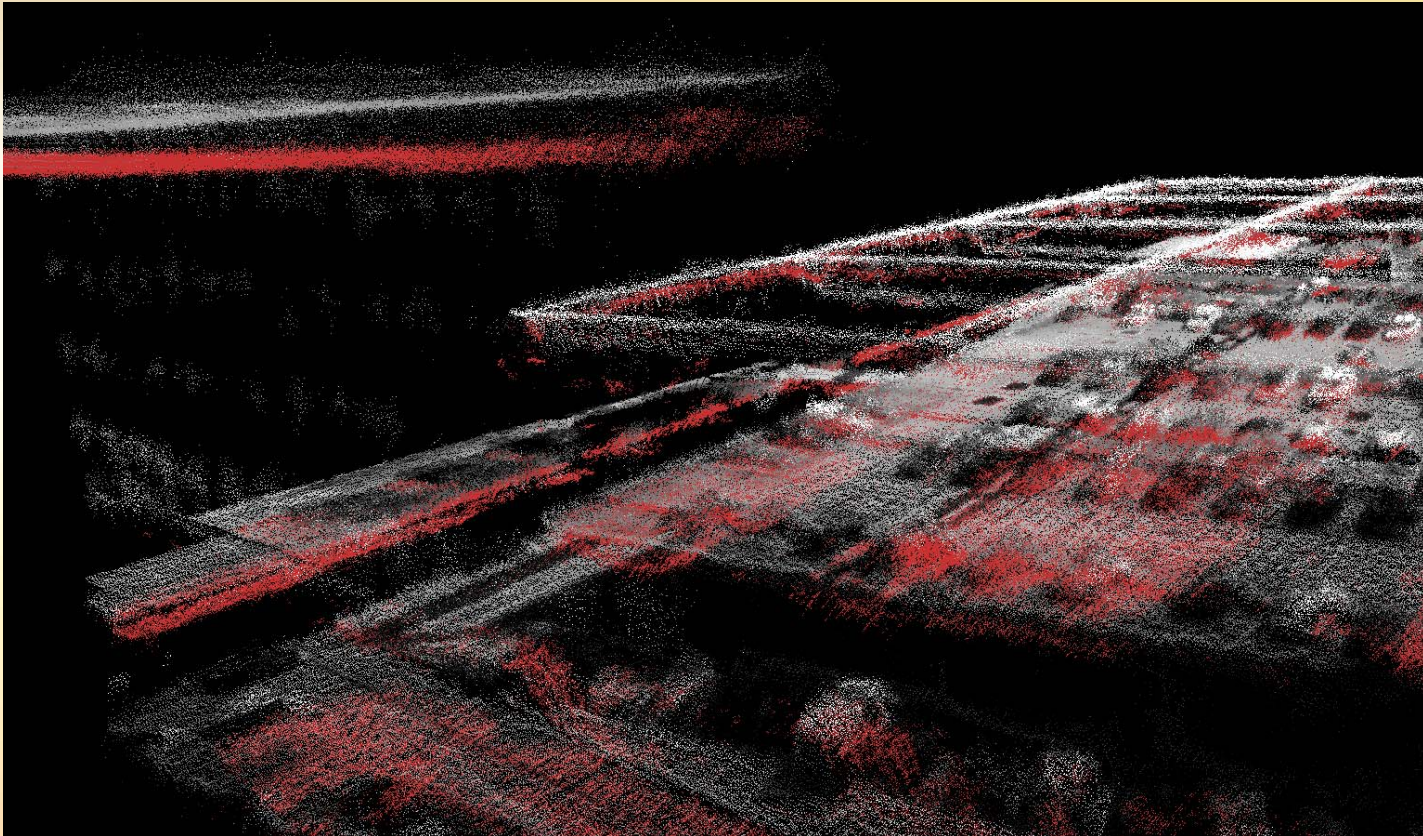
Residuals of photo measurements (x', y') in photo space:

RMS	1.9	2.4
MAX	19.1	19.3

Oblique Registration Investigations

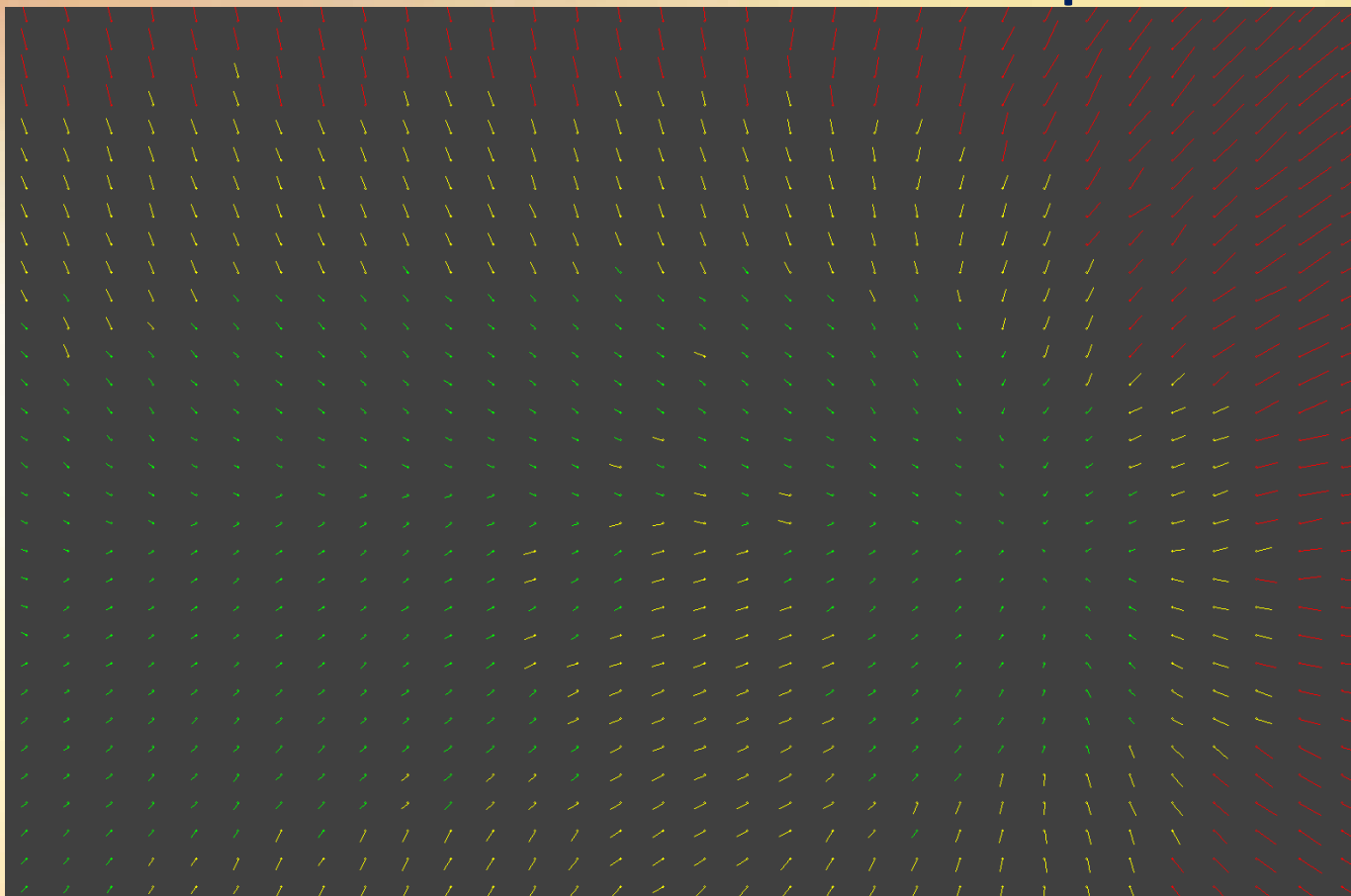
by Andreas Klaus & Joachim Bauer

**Traced reason for double structures:
systematic depth offset between nadir and
oblique images**



Salzburg UCO cam 17 before update

mean error = 1.6 max error = 7.1 pixel



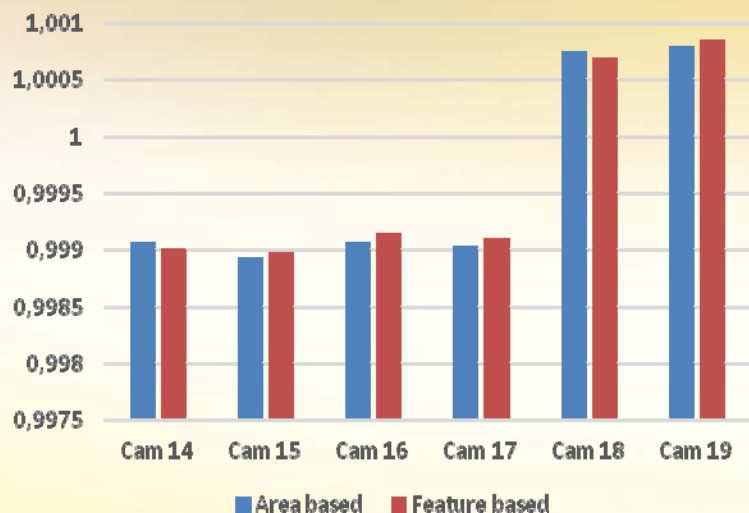
Salzburg UCO cam 17 after update

mean error = 0.48 max error = 1.8 pixel

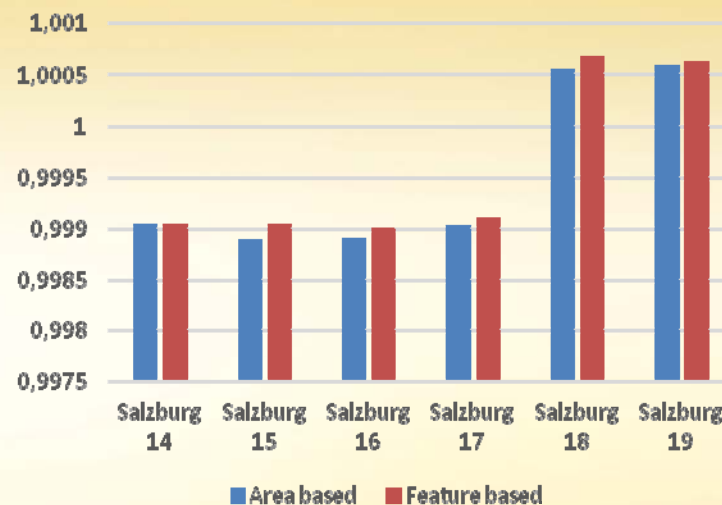


Aspect Ratios for different projects

Aspect Ratios for Graz



Aspect Ratios for Salzburg



What's causing different Aspect Ratios?

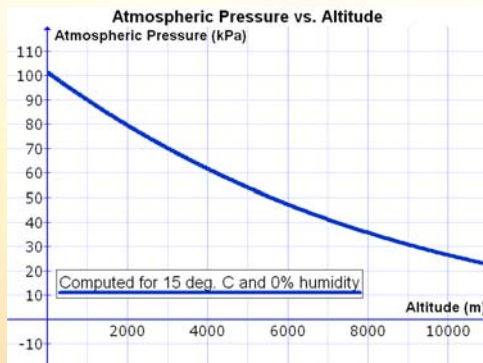
■ Earth Curvature

$y = L^2 / (2 * 6371000)$ 7,84 cm bei 1 km

1,96 m bei 5 km

7,85 m bei 10 km

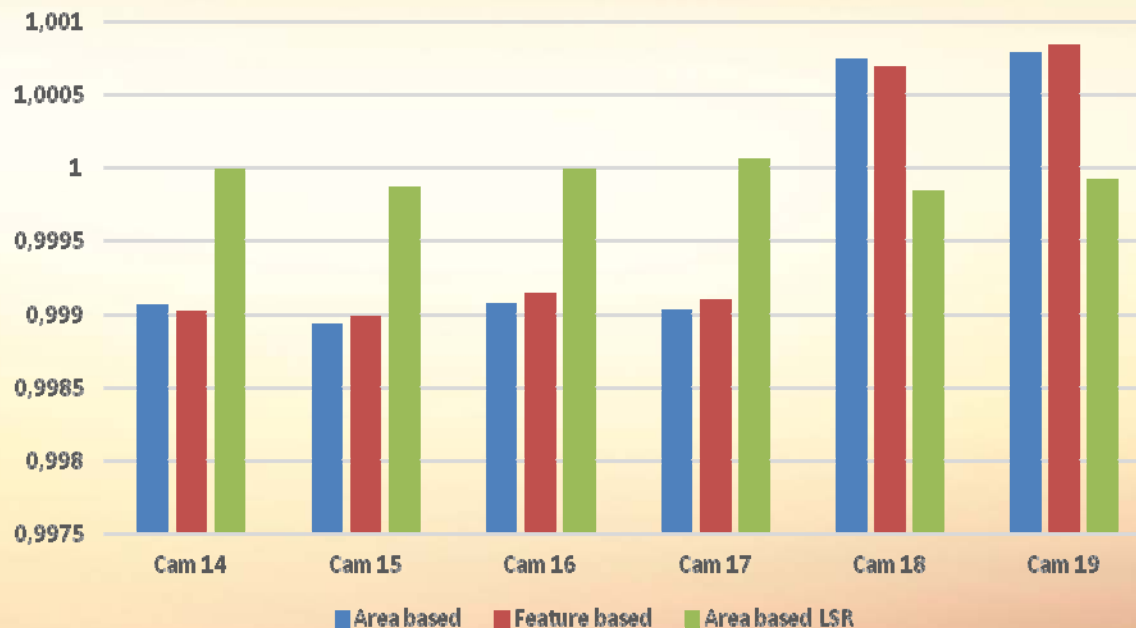
■ Atmospheric Refraction



Verification that UTM is causing deviation

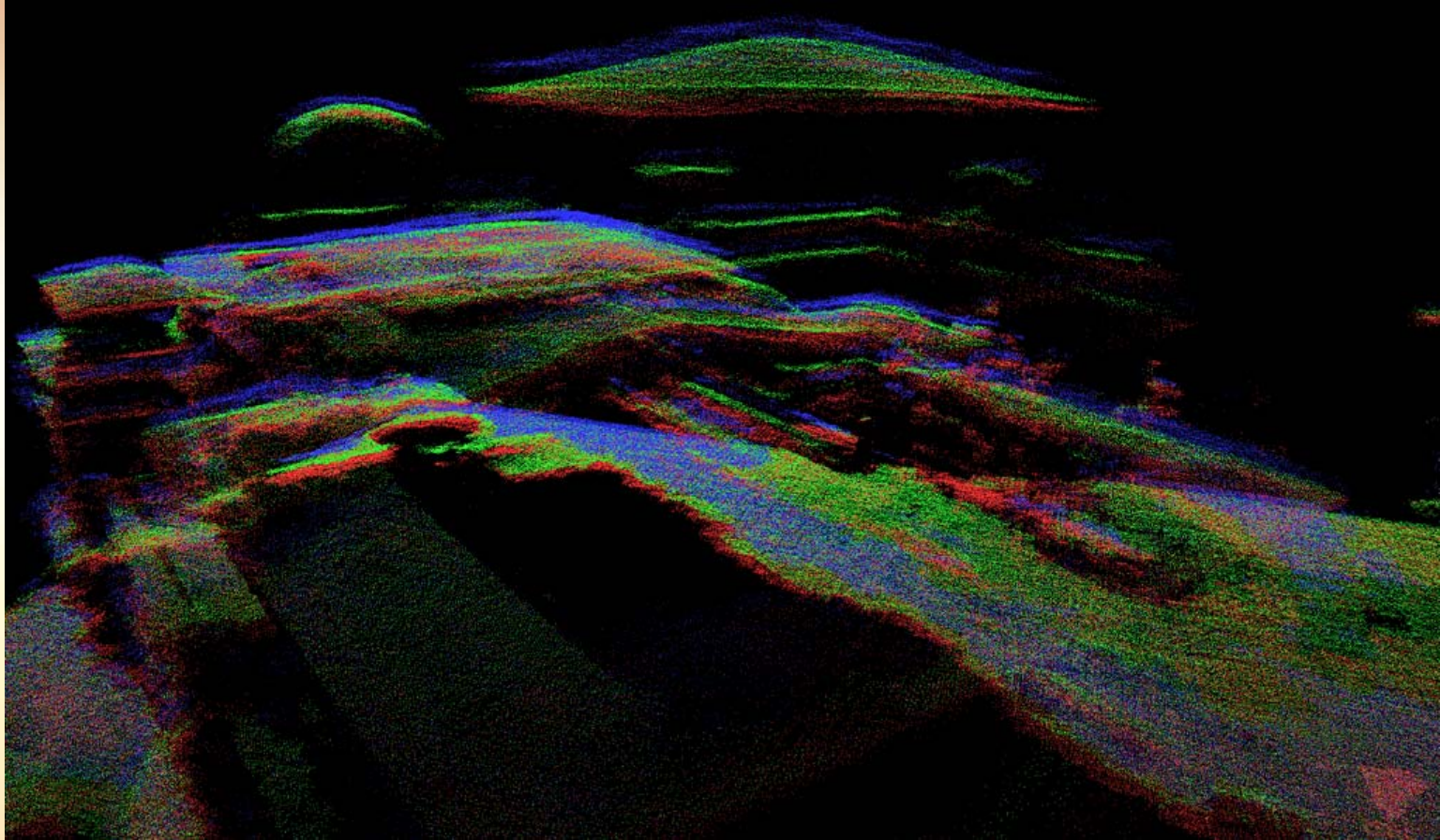
1. Processed Lvl02 for Graz without geo bias
2. Calculated new AT in LSR instead of UTM Re-processed area based Nadir-Oblique registration

Aspect Ratios for Graz: UTM vs. LSR



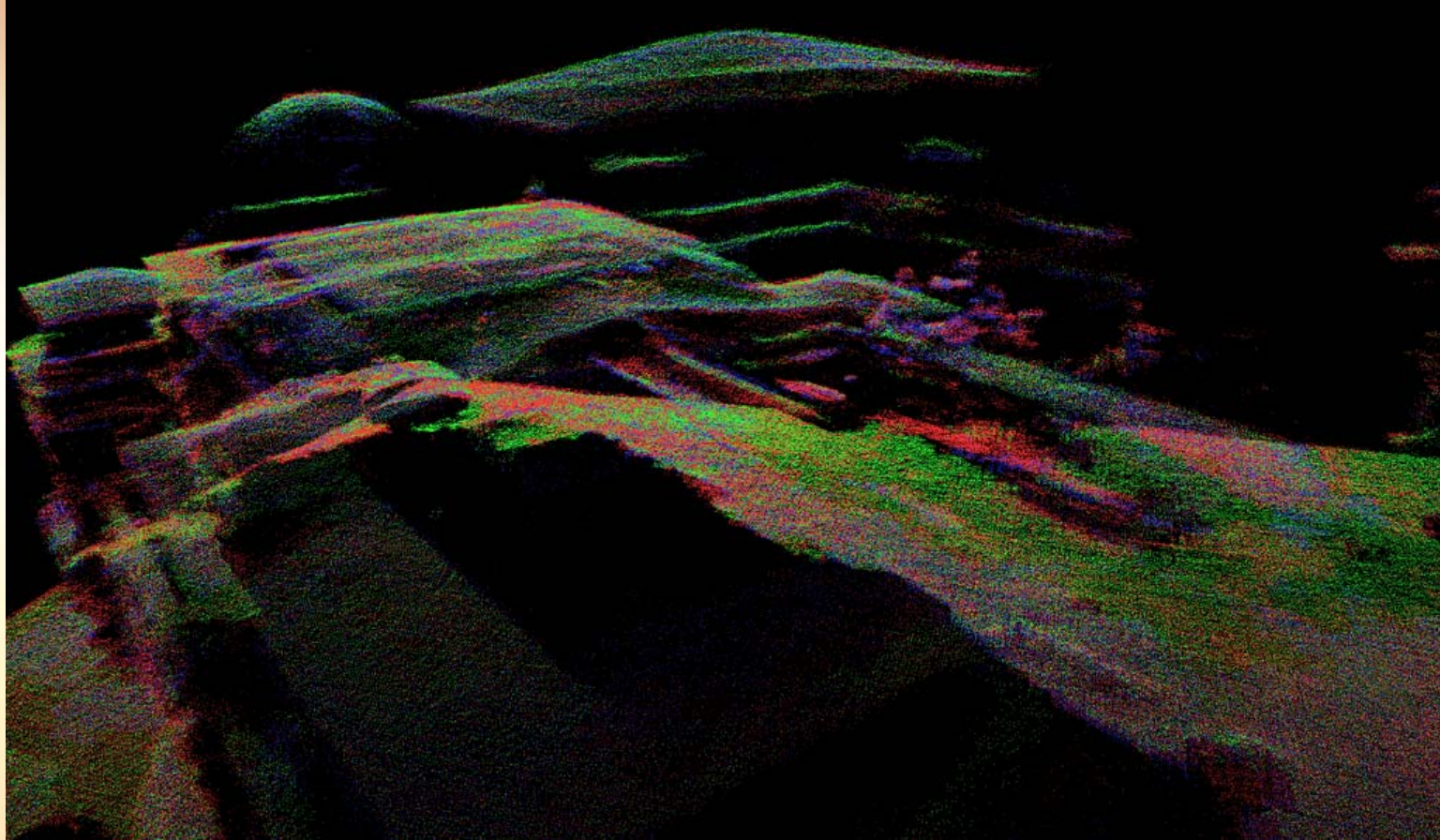
Pointcloud: UCO Graz UTM

nadir forward/backward left/right



Pointcloud: UCO Graz LSR

nadir forward/backward left/right



Conclusion

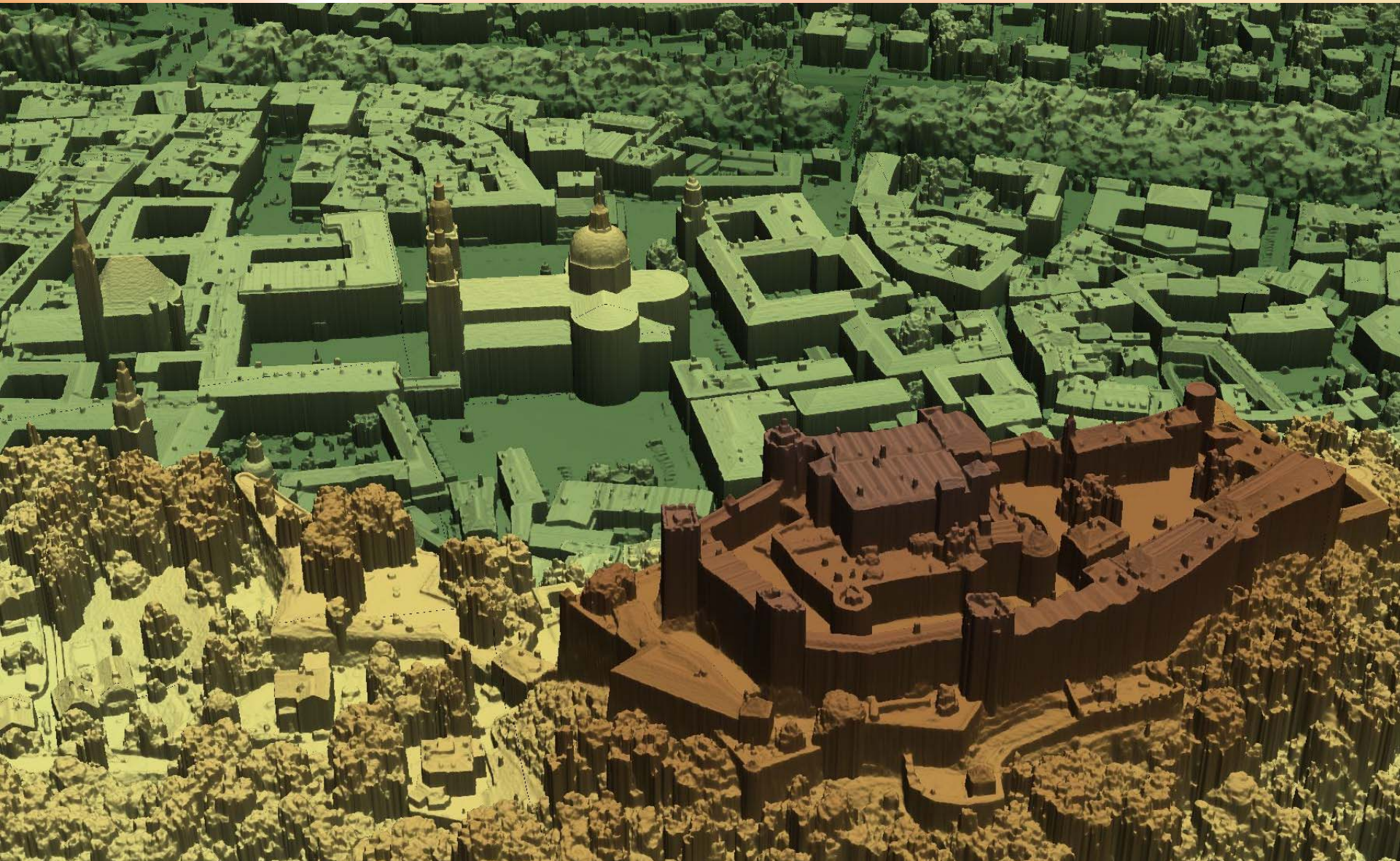
- Nadir serves as the geometry backbone
- Impact of refraction and earth curvature
- AT in UTM is problematic – especially for oblique images
- Geo bias depends on altitude, UTM zone and latitude
- LSR system allows to improve nadir-oblique registration

UltraCam Osprey Project Results

Flight Mission Salzburg, May 2013
GSD (nadir) 10,5 cm, Height AGL 890 m

Flight Pattern 75% fwd OL, 65 % sdw OL
Base 142 m, line distance 305 m





ULTRACAM



ULTRACAM







Thank you very much