



Faculty of Geodesy and Cartography
Warsaw University of Technology

Open-Source vs. Commercial Photogrammetry: Comparing Accuracy and Efficiency of OpenDroneMap and Agisoft Metashape

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EuroCOW - EUROPEAN WORKSHOP ON CALIBRATION AND ORIENTATION
IN REMOTE SENSING
16.06.2025

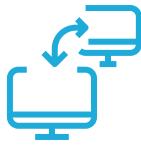


Presentation agenda



1. Background & aim of the study

Provides context and purpose for the study.



2. Technical overview

Introduces the software used in the study.



3. Study area & datasets

Describes the location and data used.



4. Methods

Outlines the procedures followed in the study.



5. Results & conclusions

Presents the findings and their implications.



1. Background & aim of the study



Background & Aim of the Study

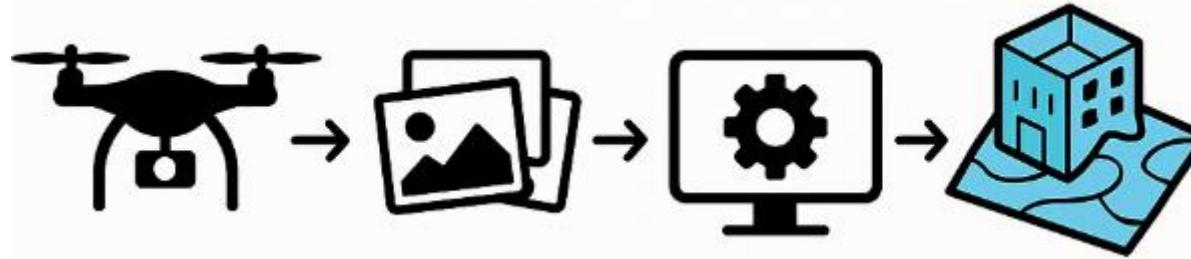


Who needs photogrammetry?





Background & Aim of the Study



Who needs photogrammetry?



Photogrammetry is everywhere - but not everyone can afford it





Cost Comparison of the most popular solutions



Agisoft Metashape
Professional Edition

Node-locked license

\$ 3 499



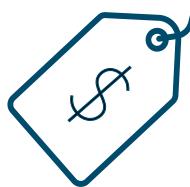
PIX4D**mapper**

Perpetual

€ 4,690 / one-time

Billed one time, excl. taxes

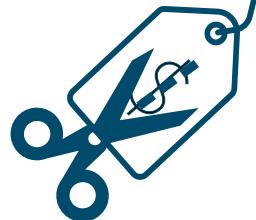
Is there a more affordable option?





Background & Aim of the Study

Can free software be as good as commercial solutions?

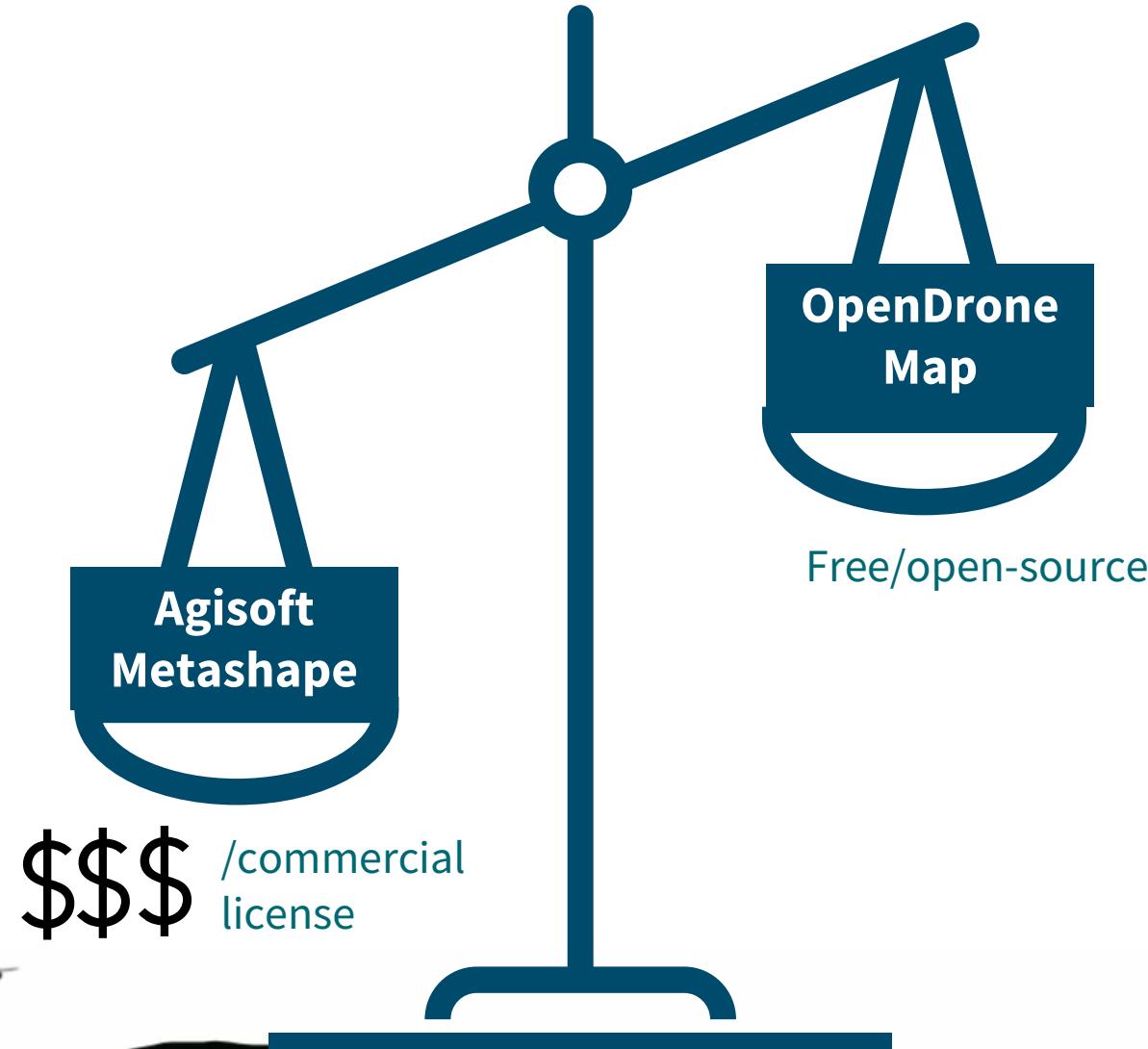




Comparison of OpenDroneMap and Agisoft Metashape

Why Compare?

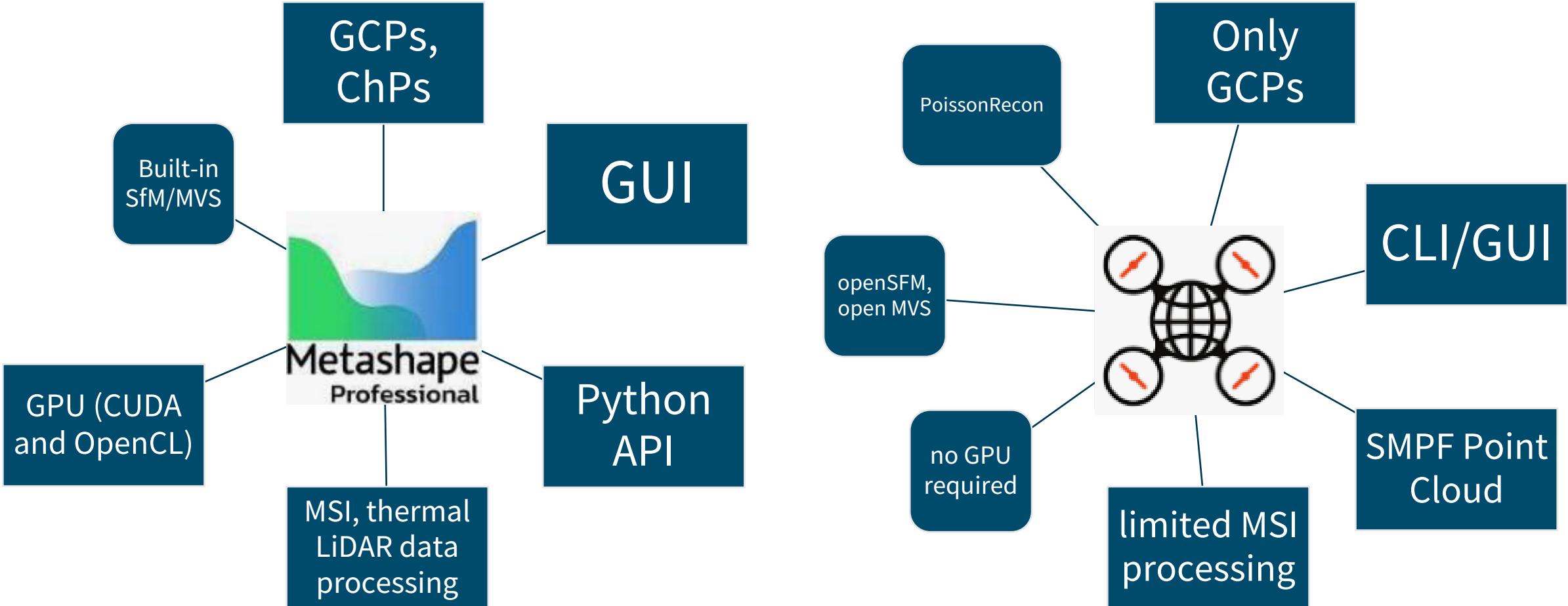
Does expensive mean better?



2. Technical overview



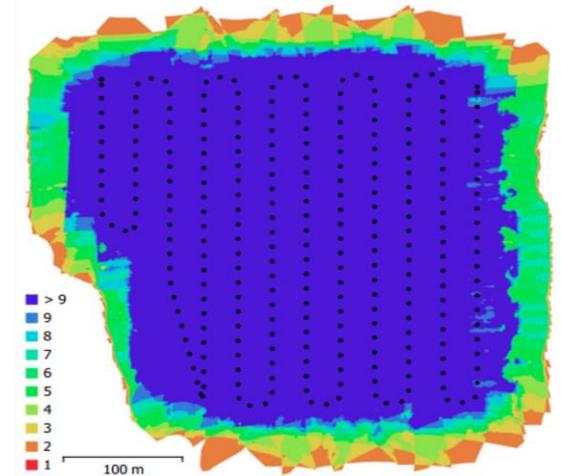
Comparison of OpenDroneMap and Agisoft Metashape



3. Study area & datasets



Study area and datasets

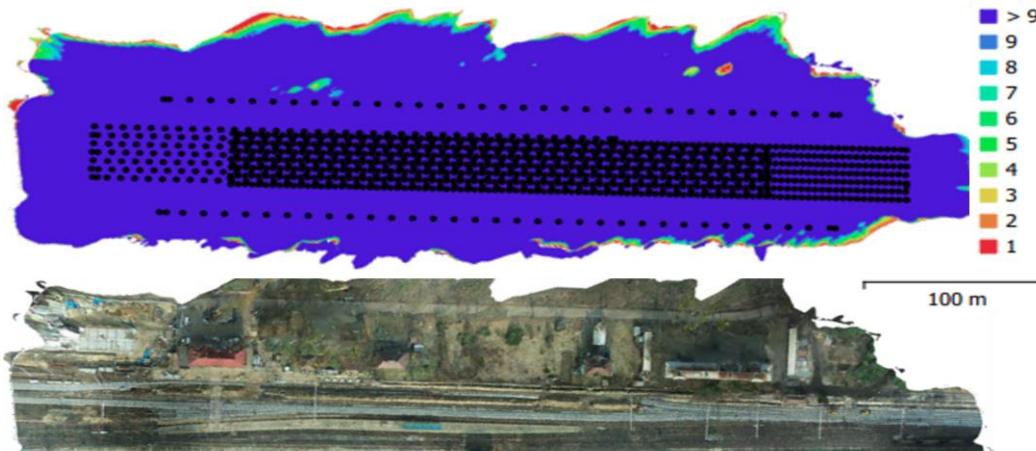


Józefosław

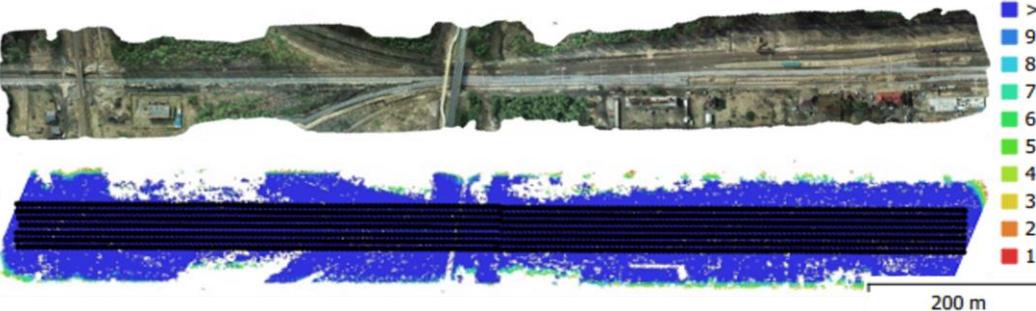
No. of scenario	1a
Dataset name	JOZE
Image type	RGB, nadir
UAV platform	DJI Mavic 3 Multispectral
Camera model	DJI M3M
GCPs and ChPs	-
Focal length [mm]	12.29
Pixel size [μm]	3.36
Image resolution	5280 x 3956
Field of view [°]	84
Image overlap [%]	85/75
Survey area [km^2]	0.024
Number of strips	12
Flying altitude [m]	87
GSD [cm]	2.2
Number of images	266
Gimbal pitch angle [°]	0



Study area and datasets



Scenarios 1b and 2b



Scenario 2a

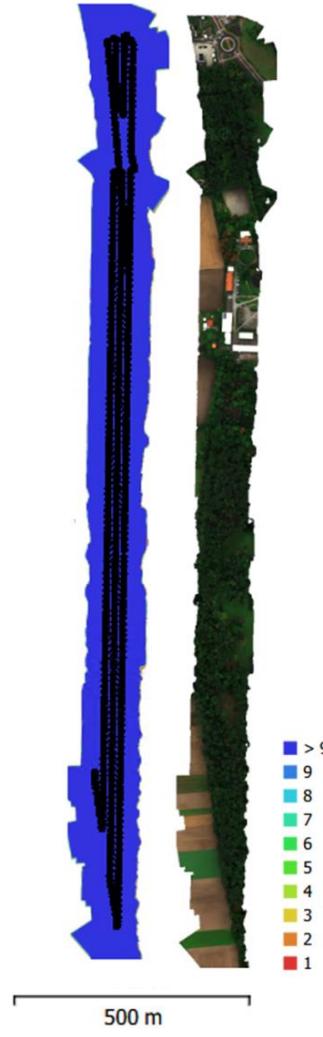


Herby

No. of scenario	1b	2a	2b
Dataset name	Herby		
Image type	RGB, oblique	RGB, nadir	RGB, oblique
UAV platform	DJI Phantom 4 RTK		
Camera model	DJI FC6310R		
GCPs and ChPs	-	57 ChPs, 7 ChPs	29 ChPs, 5 GCPs
Focal length [mm]		8.8	
Pixel size [μm]		2.41	
Image resolution		5472 x 3648	
Field of view [°]		84	
Image overlap [%]	90/90	90/90	90/90
Survey area [km^2]	0.071	0.117	0.071
Number of strips	16	7	16
Flying altitude [m]	46	56	46
GSD [cm]	1.2	1.5	1.2
Number of images	1102	1358	1102
Gimbal pitch angle [°]	45	0	45



Study area and datasets



Gołuchów

No. of scenario	3
Dataset name	Gołuchów
Image type	MSI, nadir
UAV platform	DJI Matrice 300 RTK
Camera model	Micasense RedEdge-MX Dual
GCPs and ChPs	-
Focal length [mm]	5.5
Pixel size [μm]	3.75
Image resolution	1280 x 960
Field of view [°]	47.2
Image overlap [%]	80/80
Survey area [km^2]	0.268
Number of strips	3
Flying altitude [m]	85
GSD [cm]	6.3
Number of images	500
Gimbal pitch angle [°]	0

4. Methods



Methods



Setup Scenarios

Establishing different research scenarios for testing



Test Orientation Quality

Evaluating the quality of image orientation



Test Camera Calibration

Assessing the accuracy of camera calibration



Compare Software Performance

Comparing the performance of ODM and Metashape



Analyze Calibration Accuracy

Analyzing the accuracy of calibration parameters



Visualize Distortions

Visualizing radial and tangential distortions



Scenario 1: Orientation & Calibration (No GCPs)

- 1a: RGB Nadir Imagery, Varied Pyramid Levels
- 1b: RGB Oblique Imagery, Varied Pyramid Levels

Scenario 2: Orientation & Calibration (With GCPs)

- 2a: RGB Nadir Imagery at Original Resolution
- 2b: RGB Oblique Imagery at Original Resolution

Scenario 3: Multispectral Image (MSI) Processing

- Overview of MSI Data Processing
- Calibration and Orientation of MSI Data



5. Results & conclusions



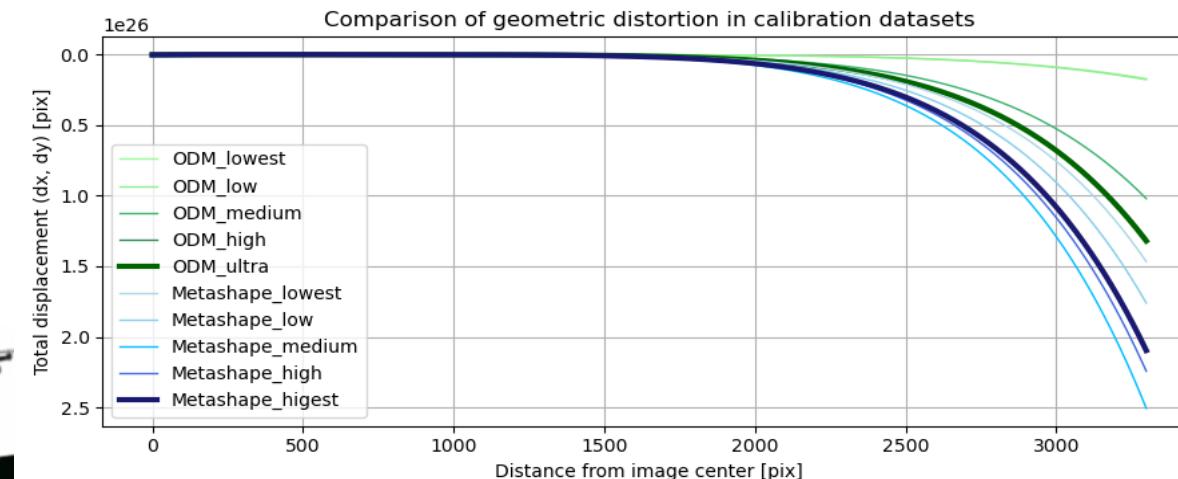
Results: Scenario 1a

The results obtained for processing scenario 1a, the JOZE dataset in the ODM software.

Level	Lowest	Low	Medium	High	Ultra
GPS error [m]	0.003	0.011	0.033	0.052	0.055
Avg. Rep Error [pix]	2.03	1.78	1.37	1.12	1.13
Focal [mm]	11.6947	11.8934	12.3245	12.4860	12.4842
Cx [μm]	8.87	7.10	7.10	8.87	8.70
Cy [μm]	-90.39	-89.06	-83.74	-81.08	-79.75
P1	-0.0001	-0.0001	-0.0001	-0.0004	-0.0004
P2	-0.0005	-0.0005	-0.0004	-0.0001	-0.0001
K1	-0.0818	-0.0928	-0.1053	-0.1094	-0.1093
K2	-0.0243	-0.0120	0.0022	0.0061	0.0062
K3	0.0028	-0.0029	-0.0167	-0.0213	-0.0216

The results obtained for processing scenario 1a, the JOZE dataset in the Metashape software.

Level	Lowest	Low	Medium	High	Highest
GPS error [m]	0.218	0.122	0.150	0.112	0.076
Avg. Rep Error [pix]	7.12	3.32	1.50	1.17	0.95
Focal [mm]	13.7726	13.0379	13.4805	13.3928	13.2718
Cx [μm]	5.36	12.92	13.06	13.63	12.10
Cy [μm]	-77.33	-102.75	-90.32	-87.96	-90.68
P1	-0.0004	-0.0004	-0.0004	-0.0004	-0.0004
P2	-0.0004	-0.0002	-0.0002	-0.0003	-0.0003
K1	-0.1303	-0.1194	-0.1292	-0.1272	-0.1250
K2	-0.0024	-0.0087	0.0158	0.0129	0.0119
K3	-0.0240	-0.0288	-0.0410	-0.0367	-0.0343





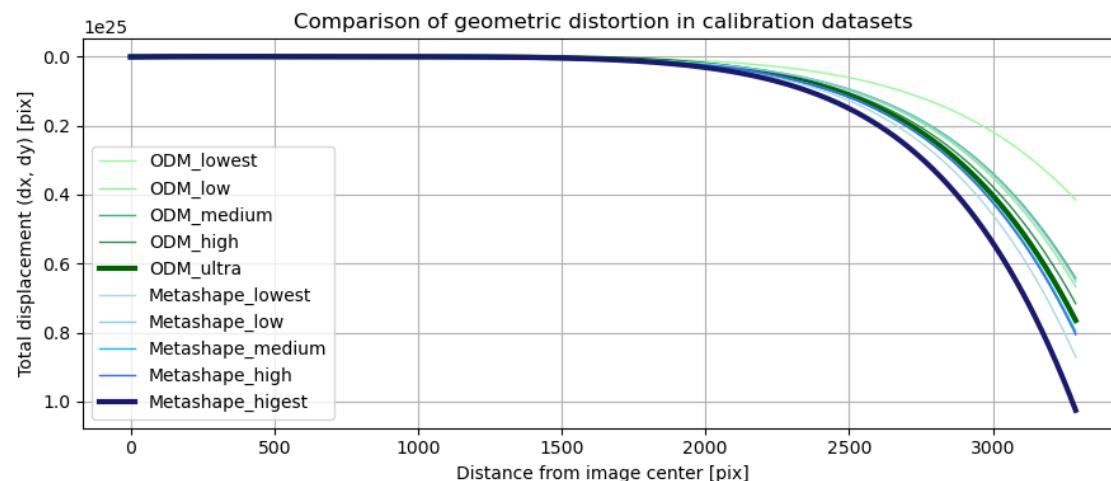
Results: Scenario 1b

The results obtained for processing scenario 1b, the Herby Oblique dataset in the ODM software.

Level	Lowest	Low	Medium	High	Ultra
GPS error [m]	0.001	0.013	0.27	0.038	0.037
Avg. Rep Error [pix]	2.12	1.81	1.41	1.15	1.16
Focal [mm]	8.9003	8.9108	8.9108	8.9095	8.9082
Cx [μm]	-13.2	-43.5	-54.1	-63.3	-64.6
Cy [μm]	12.3	5.3	6.2	6.2	7.9
P1	0.0000	-0.0003	-0.0001	-0.0001	-0.0001
P2	-0.0003	-0.0011	-0.0013	-0.0013	-0.0013
K1	-0.0122	-0.0134	-0.0142	-0.0136	-0.0134
K2	0.0003	0.0003	0.0014	0.0001	-0.0005
K3	0.0051	0.0082	0.0079	0.0088	0.0094

The results obtained for processing scenario 1b, the Herby Oblique dataset in the Metashape software.

Level	Lowest	Low	Medium	High	Highest
GPS error [m]	0.002	0.006	0.008	0.010	0.011
Avg. Rep Error [pix]	5.66	2.52	1.54	0.97	0.77
Focal [mm]	8.8923	8.8963	8.9003	8.9011	8.8992
Cx [μm]	-47.60	-44.12	-44.95	-44.77	-45.19
Cy [μm]	29.35	27.30	23.57	21.80	22.35
P1	-0.0015	-0.0015	-0.0015	-0.0015	-0.0015
P2	-0.0002	-0.0001	-0.0001	-0.0001	-0.0001
K1	-0.0128	-0.0142	-0.0132	-0.0129	-0.0119
K2	-0.0020	0.0014	-0.0008	-0.0013	-0.0045
K3	0.0107	0.0080	0.0098	0.0099	0.0126





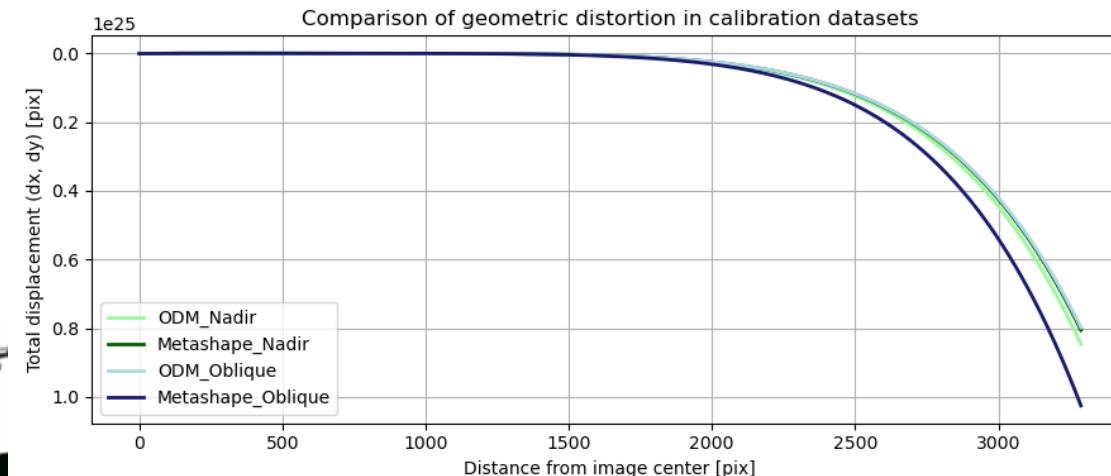
Results: Scenario 2

The results obtained for processing scenario 2a the Herby Nadir dataset with GCPs

Software & Settings	ODM (ultra)	Metashape (highest)
Total RMS GCPs [m]	0.001	0.040
Avg. Rep Error [pix]	1.19	0.61
Focal [mm]	9.1970	8.9134
Cx [μm]	5.28	-39.46
Cy [μm]	38.68	23.17
P1	-0.0001	-0.0015
P2	-0.0016	-0.0001
K1	-0.0143	-0.0157
K2	-0.0001	-0.0016
K3	0.0104	0.0099

The results obtained for processing scenario 2b the Herby Oblique dataset with GCPs

Software & Settings	ODM (ultra)	Metashape (highest)
Total RMS GCPs [m]	0.006	0.029
Avg. Rep Error [pix]	1.18	0.77
Focal [mm]	8.9121	8.8998
Cx [μm]	-54.07	-45.02
Cy [μm]	7.03	23.85
P1	-0.0001	-0.0015
P2	-0.0013	-0.0001
K1	-0.0134	-0.0118
K2	-0.0007	-0.0045
K3	0.0098	0.0126





Results: Scenario 2

The results obtained for processing scenarios 2a and 2b on GCPs.

Software & Image type	RMSE GCPs [m]			
	X	Y	Z	Total
ODM nadir	0.001	0.000	0.001	0.001
Metashape nadir	0.025	0.026	0.018	0.040
ODM oblique	0.002	0.010	0.004	0.006
Metashape oblique	0.015	0.009	0.023	0.029

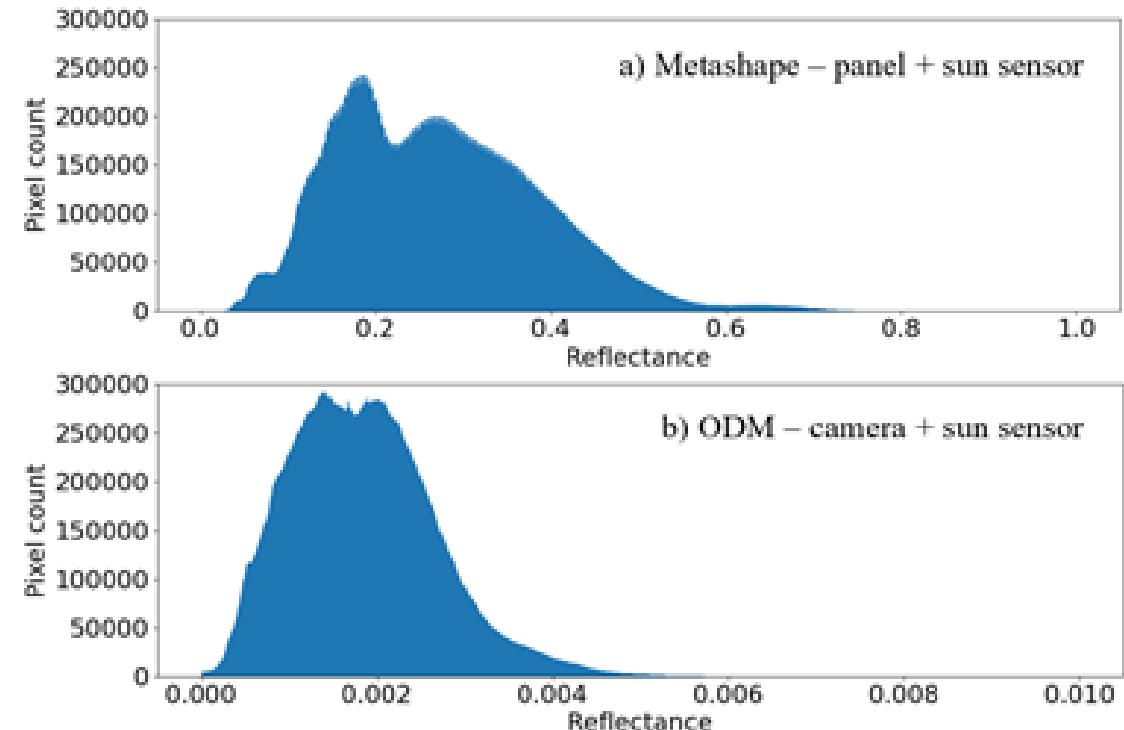
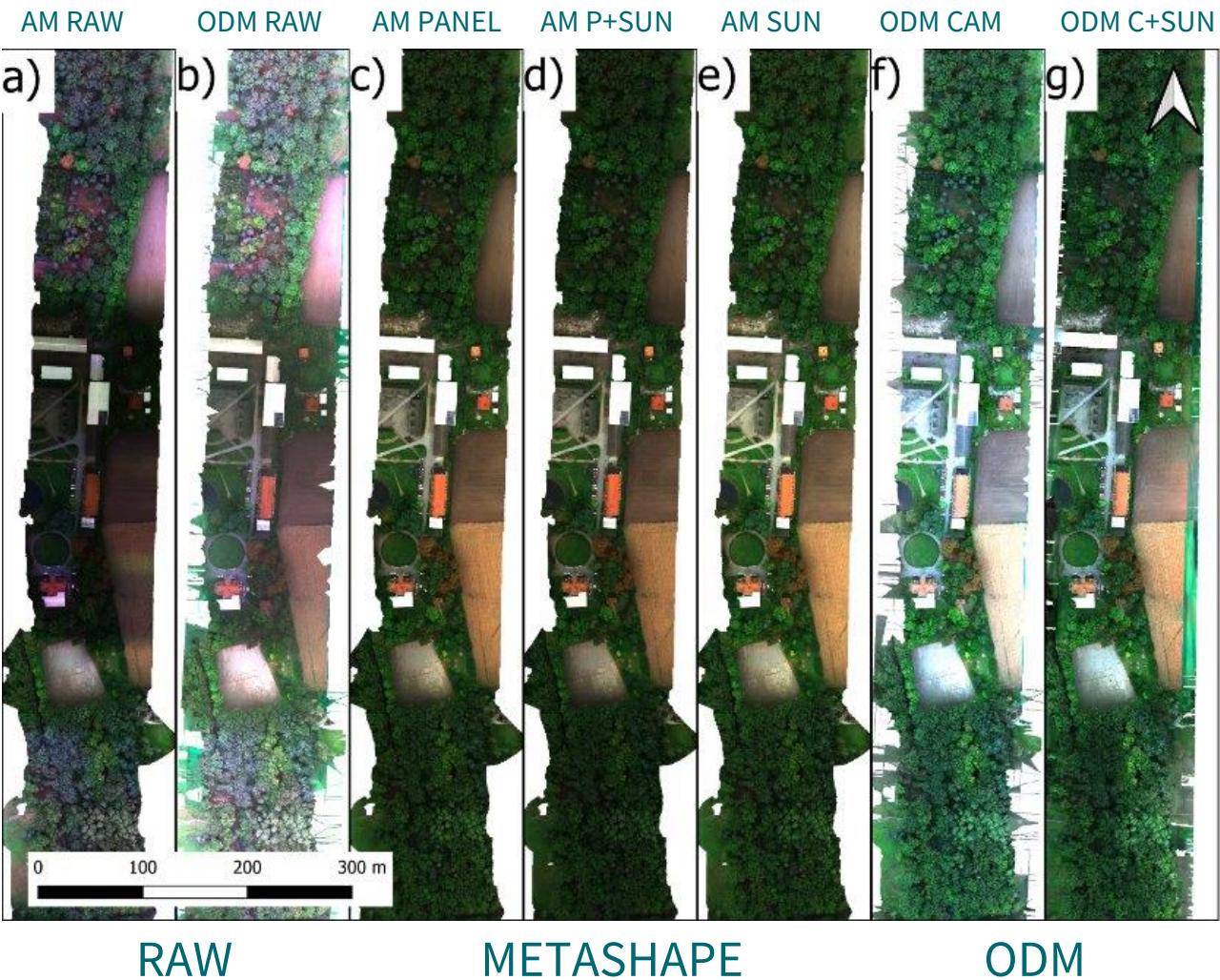
The results obtained for processing scenarios 2a and 2b on Check Points.

Software & Image type	RMSE Check Points [m]			
	X	Y	Z	Total
ODM nadir	0.032	0.044	0.038	0.067
Metashape nadir	0.022	0.016	0.026	0.038
ODM oblique	0.045	0.063	0.036	0.085
Metashape oblique	0.018	0.010	0.026	0.033





Results: Multispectral imagery processing



ODMs ability to perform radiometric calibration is limited to correction of exposure changes and use of sun sensor data without reference panels. In practice, the radiometric values are consistent within the mosaic, but the absolute values of reflectance are questionable.



Conclusions



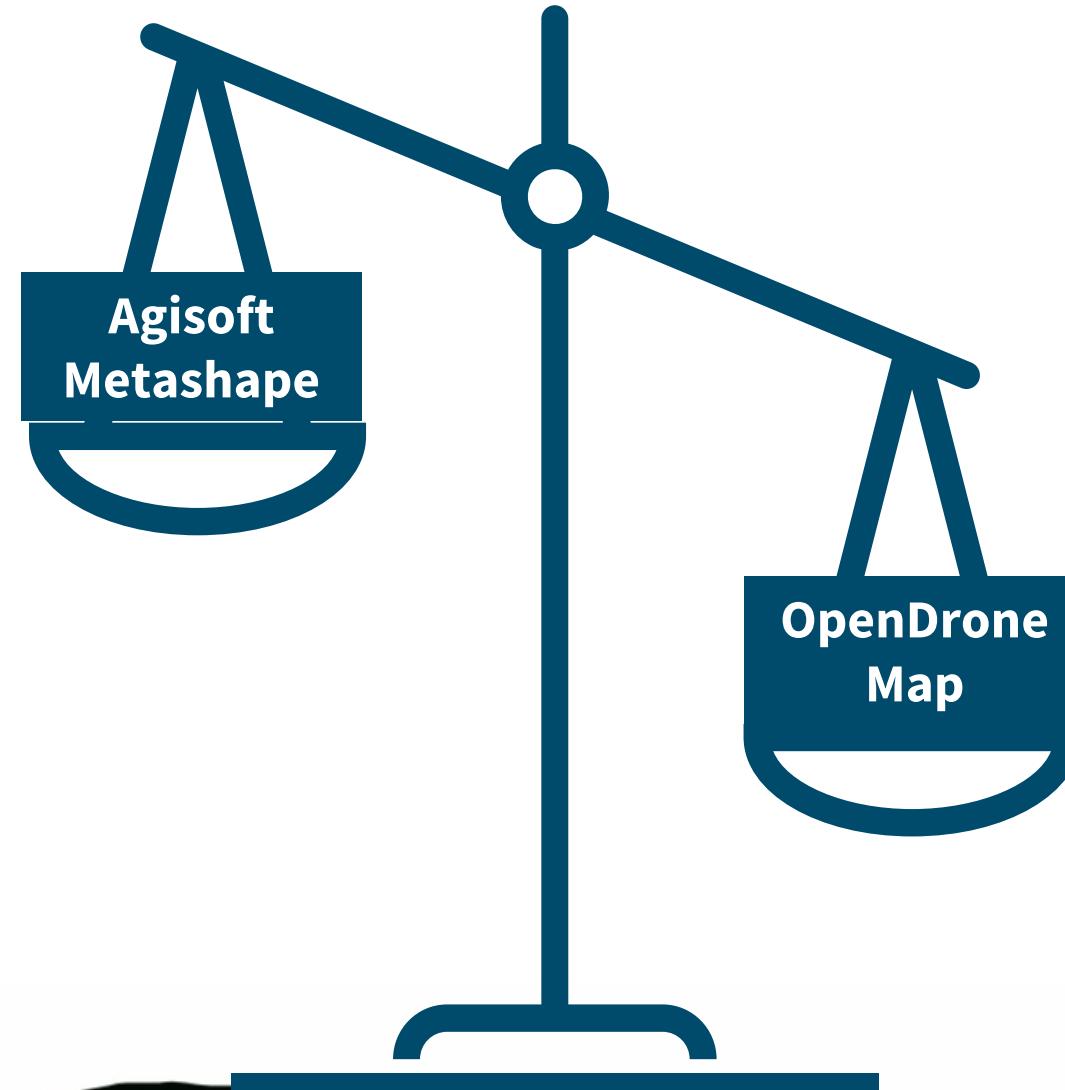
Comparable
Calibration
Results



Limited
Georeferencing



Basic MSI
Processing



Advanced
Calibration Tools



Robust
Georeferencing



Comprehensive
MSI Processing



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Thank you for
your attention



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